



Extending a Missions and Means Framework (MMF) Demonstration to Vulnerability/Lethality Data Production

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Objective



To present the data production process for the 2005 MMF demonstration and how lessons learned can be applied in the future.



Outline



- > MMF: What's different
- > Demonstration Models and Data
- > Data Development Process
- > Status
- > Implications



MMF Demonstration:

What's Different?

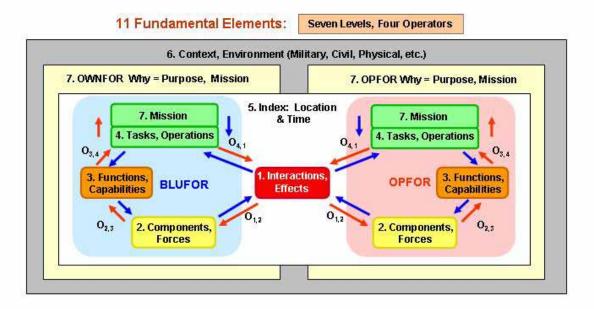


- Direct application of war fighter tasks.
- Demonstration of network-centric effects that features SoS-level fault trees

Degraded Capability States (DCS) at both platform and component levels

Dynamic effects of vulnerability, reliability, repair, ...

Alternative courses of action







MMF Data: What's Different?



Traditionally

- System developer, user and evaluator determine a Damage Assessment List of critical Line-Replaceable-Units (LRU).
- A conclave is formed to assign a weighting to each LRU representing the loss to mission effectiveness across all scenarios and environment conditions.
- Limiting metrics; mobility, firepower, communications and catastrophic.
- Developmental test information was not incorporated into V/L modeling.

What's NEW

- Data development is directly correlated to the Army Universal Task List (AUTL), Joint Universal Task List (UJTL) or Lead System Integrator tasks.
- Expanded metrics support a robust system representation required for a system of systems evaluation and training.
- A closer communication between the modeling, testing and soldier community.

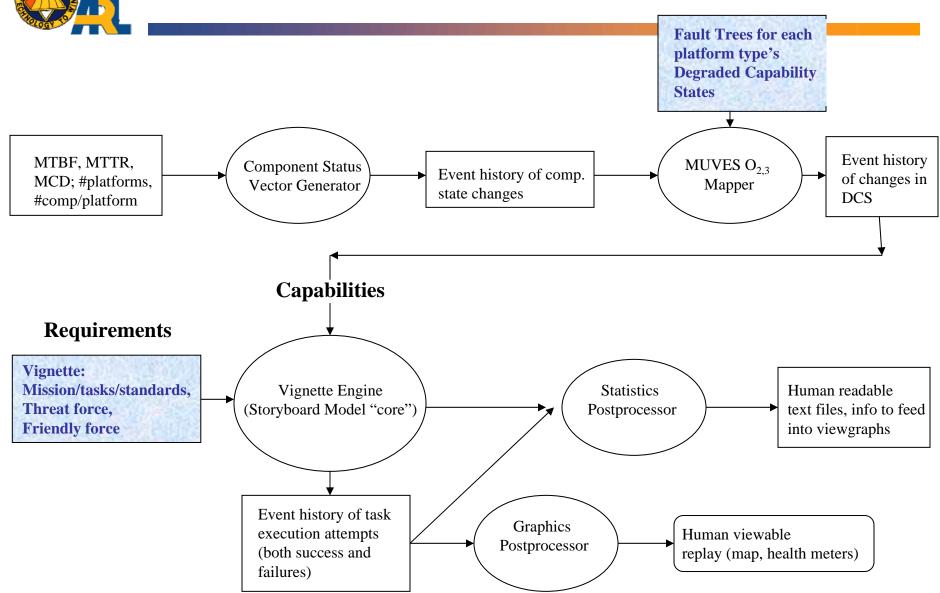
What's missing is metric validation via developmental testing.



MMF Demonstration:



Models and Data





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Overview

- 1. Determine platform engineered capability elements (engineer/design contractor).
- 2. Perform criticality analysis and develop system fault trees (engineer/analyst).
- 3. Determine semantic and design constraints (engineer/analyst).
- 4. Develop the DCS partially ordered set (Poset) given the constraints (analyst).
- 5. Determine the appropriate tasks typical for platform (AUTL/UJTL).
- 6. Determine the required DCS for each tasks and color code acceptability (TRADOC System Manager).
- 7. Bin the platform poset by tier and acceptability.
- 8. Calculate the probability of available capability at 3 levels (red, amber, green) for each platform task per threat (analyst).

Process requires closer communications between the modeling, analysis, testing, and training communities.



Degraded Capability States:

Basic Elements





C2V (2)



NLOS (6)



ARV-RISTA
(3)



Mobility (5)

M0 No Mobility Degradation
M1* Reduced Maximum Speed
M2 Reduced Maneuverability
M3* Stop After T Minutes
M4 Reduced Acceleration
M5 Total Immobilization

Firepower (12)
F0 No Firepower Degradation
F1 Lost Ability To Fire Buttoned Up Main
F2 Degraded Delivery Accuracy of Main
F3 Degraded Initial Rate of Fire of Main
F4 Degraded Subsequent Rate of Fire of Main
F5 Degraded Maximum Range Main
F6 Lost Reload Capability
F7 Total Loss of Firepower Main
F8 Lost Ability to Fire Buttoned Up Secondary
F9 Degraded Delivery Accuracy of Secondary
F10 Degraded Initial Rate of Fire of Secondary
F11 Degraded Subsequent Rate of Fire of Secondary
F12 Total Loss of Firepower Secondary

Communication (8)

X0 No Communication Degradation
X1 Reduced Range
X2* Lost Line-of-Sight (LOS) Data (ex. JTRS)
X3* Lost LOS Voice
X4* Lost Non-LOS Data (ex. SATCOM)
X5 Lost NLOS Voice

AS LOST NLOS VOICE

X6 Lost Internal Communications X7 Lost External Communications X8 Lost All Communications

S0 No Survivability Degradation

Survivability (6)

S1 Lost NBC Protection S2 Lost Ability to Deploy Obscurants S3 Lost Silent Watch Capability S4 Lost Active Protection System S5 Lost Threat Warning Capability S6 Lost Fire Suppression Capability

<u>Target Acquisition</u> (3)

A0 No Acquisition Degradation A1 Lost Daylight Sights A2 Lost Night Sights A3 Lost Range Finder

Surveillance (4)

Z0 No Surveillance Degradation
Z1 Lost Primary Sensor
Z2 Lost Secondary Sensor
Z3 Lost Tertiary Sensor
Z4 Lost All Surveillance

Crew (7)

C1 Commander Incapacitated
C2 Squad Leader Incapacitated
C3 Driver Incapacitated
C4 Operator 1 Incapacitated
C5 Operator 2 Incapacitated
C6 Gunner Incapacitated

C7 Loader Incapacitated

C0 No Crewmember Incapacitated

Passengers (1)

P0 No Passengers Incapacitated P1 Passengers Incapacitated

$\underline{\text{Other}}(3)$

01 Lost Situational Awareness
 02 Lost Unmanned System Control
 03 Lost Automated C²

Catastrophic Loss (1)

K0 No Catastrophic Loss K1 Lost Every Capability

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^{*} assigned degradation factor according to the variation in components affecting speed or bandwidth.





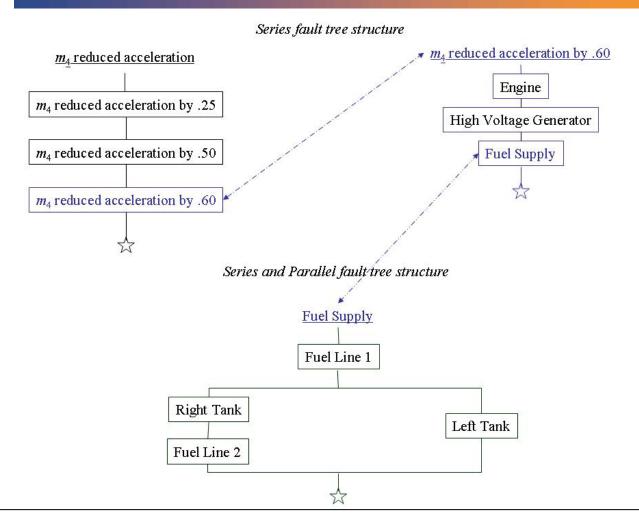
Determine Engineered Capabilities

Category	<u>Description</u>	ARV (RSV)	<u>UAV</u>	<u>C2V</u>	NLOS-C
Mobility					
m1	reduced_maximum_speed	X	x	X	X
m2	reduced_maneuverability	X	x	X	X
m3	stop_after_t_minutes (leaks)	X	x	X	X
m5	total_immobilization	X	X	X	X
Firepower					
f1	lost_ability_to_fire_buttoned_up_main	X		X	
f2	degraded_delivery_accuracy_main				X
f3	degraded_initial_rate_of_fire_main				X
f4	degraded_subsequent_rate_of_fire_main				X
f 7	total_loss_of_firepower_main	mg		mg	howitzer
f12	lost_secondary_armament				X
Communications					
x2	lost_external_data	X	x	X	X
х3	lost_external_voice			X	X
x6	lost_internal_comms			X	X
x8	lost_all_commo			X	X





Criticality Analysis and DCS Fault Tree Development



NLOS-C mobility is increased by hybrid electric technology.



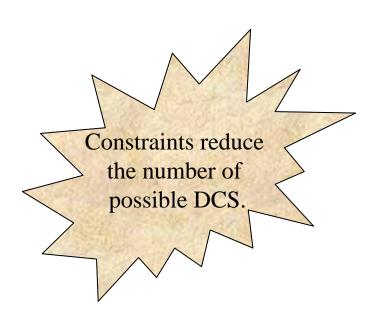


Determine Constraints

- SEMANTIC constraints imply loss by definition.
 - i.e., if x_7 then x_1 , x_2 , x_3 , x_4 and x_5 .
- DESIGN constraints imply loss of capability by the engineered component relation.

i.e., if
$$x_2$$
 then x_3

ID	COMMUNICATION CAPABILITY
X_0	No Communication Degradation
X_1	Reduced Range
X_2	Lost Line-of-Sight (LOS) Data
X_3	Lost LOS Voice
X_4	Lost Non-LOS Data
X_5	Lost NLOS Voice
X_6	Lost Internal Communications
X_7	Lost External Communications
X_8	Lost All Communications

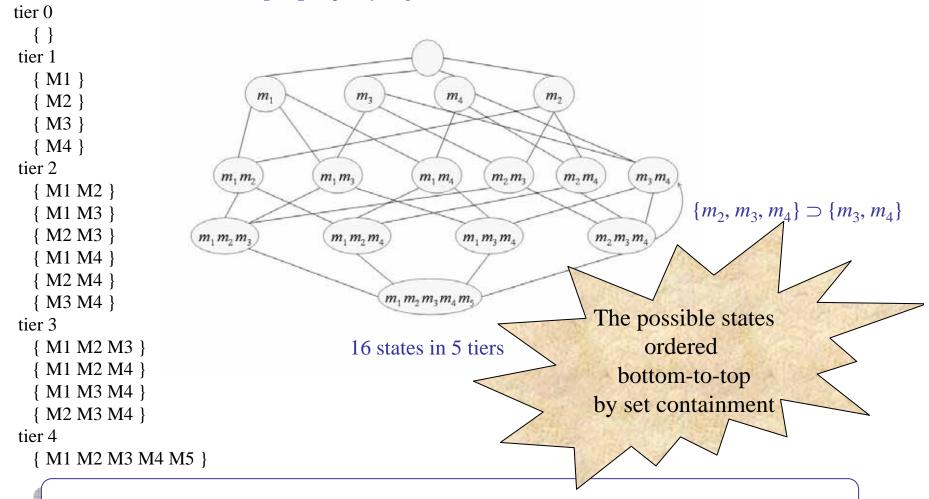






Develop Partially Ordered Sets

Of the $2^5 = 32$ subsets of $\{m_1, m_2, m_3, m_4, m_5\}$, the constraint preclude all but these 16:



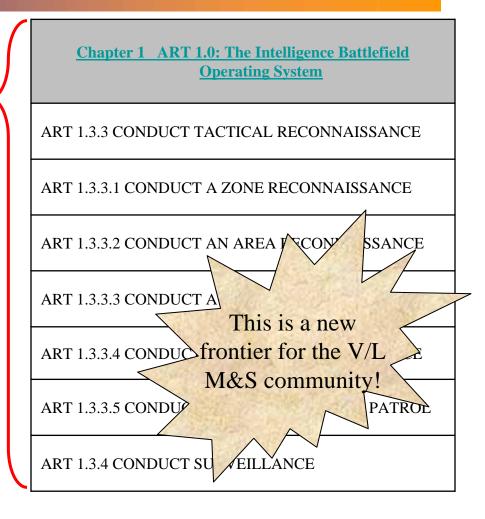
How the NLOS-C mobility states compare for capability.





Determine Appropriate Tasks

Sub-Class	
Ground System	
ed Ground System	
Air System	
ed Air System	
ire	
Fighting ehicle/Armored Personnel arrier	
ck	
Fire	
ed Ground System	
Ground System	
Fuel Truck	
ruck	
ty	
Evacuation	
el Carrier	



Requires (approval or) buy-in from the user community.

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Platform Tasks to Capability Matrix*

		TASKS Current tasks	Min Performing Task]	MOBILITY	Y (ART 2.2	<u>!</u>)	
	$lacksquare egin{array}{c} lacksquare $	determine which states are adequate.		m0	m1	m2	m3	m4	m5
02:00-03:40, 03:51-04:17	ART 2.2	*LSI A1.2 Conduct Tactical Maneuver ART 2.2	126	m0	m1	m2	m3	m4	m5
			0.25			(m1 -	+ m2)		
03:41-03:51, 04:20-10:00	ART 2.5	LSI A1.5.2 Occupy an Attack/Assault Position ART 2.5.2	350 0.68	m0	m1	m2	m3	m4	m5
03:41-03:51, 04:15-04:25	ART 3.3	*ART 3.3.1.1 Conduct Surface to Surface Attack	20						
03:47-03:52, 04:22-04:27, 04:38-04:43	ART 3.3	MTP 06-5-A008 Conduct Fire Missions	0.04						

Total minutes working tasks for NLOS-C in vignette =

* MMF Demonstration

93% of the NLOS-C mission required some mobility.

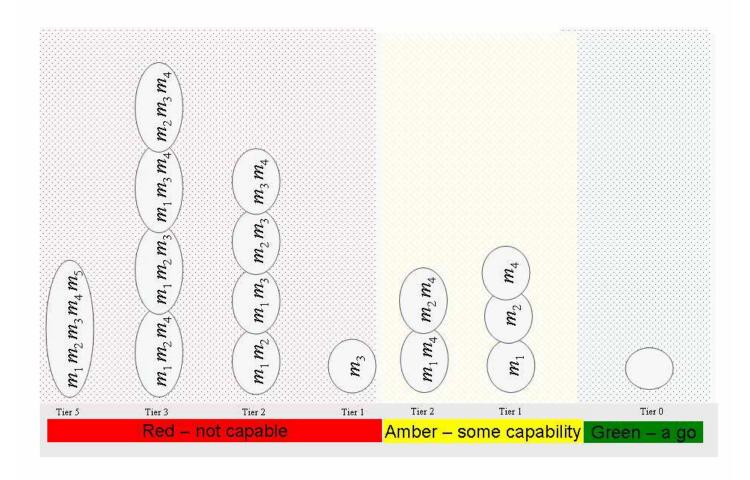
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Bin poset for Each Task

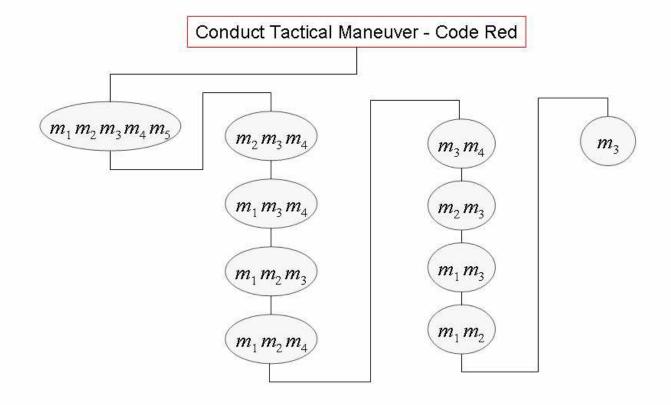
For task ART 2.2 LSI A1.2 Conduct Tactical Maneuver *.







Task-based Fault Tree Development







Calculate Probability of Degradation

TASK		Threat A			
		A	G		
ART 2.2 Conduct Tactical Maneuver	.11	.15	.74		
ART 2.5.2 Occupy Attack/Assault Position	.13	.14	.73		
ART 3.3.1.1 Conduct Surface to Surface Attack	.21	.15	.64		
MTP 06-5-A008 Conduct Fire Missions	.21	.15	.64		
Mission Health Average	.17	.15	.68		

Ballistic vulnerability as it relates to mission tasks.

Ballistic vulnerability as it relates to platform capability.

Capability	Threat A			
	R	A	G	
Mobility	.20	.08	.72	
Communications	.01	.04	.95	
^ Crew	.00	.03	.97	
Catastrophic	.04	N/A	N/A	

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Data Development Status



- ➤ Battlefield Operating Systems (BOS) have been mapped to platform subclasses, individual platforms in those classes, and associated tasks; database of this information is under development.
- ➤ ARL will be visiting Combined Arms Command (CAC) and the Futures Center to foster collaboration (BOS and AUTL/UJTL to platform assignment).
- > There are plans to collaborate with TRADOC schools.
- > ARL is developing MMF data for select Current Force systems.
- > Several related M&S tools are under development to improve input development and results analysis.

The T&E community can leverage from these activities.



Implications



- > AUTL used for MMF can be used to support Operational Testing, i.e., what the system is supposed to do.
- ➤ Information from Developmental Testing can be incorporated into V/L modeling and validate Degraded Capability States.
- The same V/L modeling can be used to provide pre-shot predictions and support post-shot analysis during LFT&E.
- > Low level tasks derived from an authoritative source such as the AUTL could be incorporated into Force-Level scenario development.
- ➤ The V/L data that supports the Force-level modeling could also be based on the same AUTL.

System evaluation would have an auditable trail while reducing inconsistency and risk.